## 2. CONTROL ENGINEERING Author: Prof. Madan Gopal

S. CD **Title** No. No. 1. Introduction to Control Problem 627 2. **Basic Feedback Structure** 628 3. Introduction to Control Problem (Contd.) 629 4. Dynamic System and Dynamic Response 630 5. Dynamic Systems and Dynamic Response (Contd.) 631 632 6. Dynamic Systems and Dynamic Response (Contd.) Dynamic Systems and Dynamic Response (Contd.) 633 7. 8. Dynamic Systems and Dynamic Response (Contd.) 634 9. Dynamic Systems and Dynamic Response (Contd.) 635 10. Modes of Industrial Control Devices and Systems 636 Models of Industrial Control Devices and Systems (Contd.) 11. 637 12. 638 Models of Industrial Control Devices and Systems (Contd.) 13. 639 Models of Industrial Control Devices and Systems (Contd.) 14. Models of Industrial Control Devices and Systems (Contd.) 640 15. Models of Industrial Control Devices and Systems (Contd.) 641 642 16. Models of Industrial Control Devices and Systems (Contd.) 643 17. Models of Industrial Control Devices and Systems (Contd.) Models of Industrial Control Devices and Systems (Contd.) 18. 644 19. Basic Principles of Feedback Control 645 20. Basic principles of Feedback Control (Contd.) 646 21. Basic principles of Feedback Control (Contd.) 647 22. Basic principles of Feedback Control (Contd.) 648 23. 649 Concepts of stability and Routh Stability criterion Concepts of Stability and Routh Stability Criterion (Contd.) 24. 650 25. 651 Concepts of Stability and Routh Stability Criterion (Contd.) 26. The Performance of Feedback Systems 652 27. The Performance of Feedback Systems (contd.) 653 28. The Performance of Feedback Systems (contd.) 654 29. The Performance of Feedback Systems (contd.) 655 30. 656 Compensator Design Using Root Locus Plots 31. Compensator Design Using Root Locus Plots (Contd.) 657 32. Compensator Design Using Root Locus Plots (Contd.) 658 33. 659 Compensator Design Using Root Locus Plots (Contd.) 34. Compensator Design Using Root Locus Plots (Contd.) 660 35. The Nyquist Stability Criterion and Stability Margins 661 36. The Nyquist Stability Criterion and Stability Margins (Contd.) 662 37. The Nyquist Stability Criterion and Stability Margins (Contd.) 663 38. The Nyquist Stability Criterion and Stability Margins (Contd.) 664 39. Feedback System performance Based on the Frequency Response 665 40 Feedback System performance Based on the Frequency Response (Cont) 666 41. Compensator Design Using Frequency Response Plots 667

**UNIT: 41**